

Some materials science (3 cpu) *LM00EE87*

Hiukan materiaalitiedettä

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Lectures 18 h, exercises 28 h, literature and examination 28 h

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I Tensorial elasticity

Boundary displacement
Original length
Engineering strain

True strain, infinitesimal strain

Total differential of displacement, Cauchy strain tensor
Symmetry

Force
Gross-sectional area
Engineering (nominal) stress

Total differential of force, Cauchy stress tensor
Symmetry

Total differential of strain, Compliance
Total differential of stress, Stiffness

Symmetry of Compliance and Stiffness
Orthotropic material symmetry
Co-ordinate transformations of Strain, Stress, Compliance and Stiffness

II Newtonian Flow

Internal friction of fluid
Newtonian viscosity
Darcy's Law
Fick's Law and Divergence Theorem
Hagen-Poiseuille law

III Diffusion

Divergence Theorem
Diffusion Equation
Continuity Equation
Thermal Flux Equation
Thermal Conductivity Equation

Scaling use of the Diffusion Equation
Solving the Diffusion Equation

Tensorial elasticity

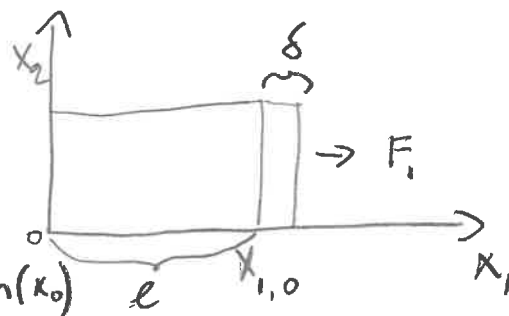
Boundary displacement δ , displacement u

Original length l , $x_{i,0}$

Engineering strain

$$e_i = \frac{\delta}{l} = \frac{\delta}{x_{i,0}}$$

Large strain (true large strain)

$$\mathcal{E} = \int_{x_0}^{x_0+u} \frac{dx}{x} = \int_{x_0}^{x_0+u} \ln(x) = \ln(x_0+u) - \ln(x_0)$$


$$= \ln \frac{x_0+u}{x_0} = \ln \left(1 + \frac{u}{x_0} \right) \quad \text{True Strain}$$

$$\hookrightarrow \ln(1+e)$$

True strain, infinitesimal strain, local strain

$$e = \frac{u}{x_0} \quad \text{Engineering Strain}$$

$$E_{ij} = \lim_{\Delta x_j \rightarrow 0} \frac{\Delta u_i}{\Delta x_j} = \frac{\partial u_i}{\partial x_j}$$

$$\delta_i = u_i = \int_0^{x_{i,0}} \frac{\partial u_i}{\partial x_j} dx_j = \int_0^{x_{i,0}} E_{ij} dx_j$$

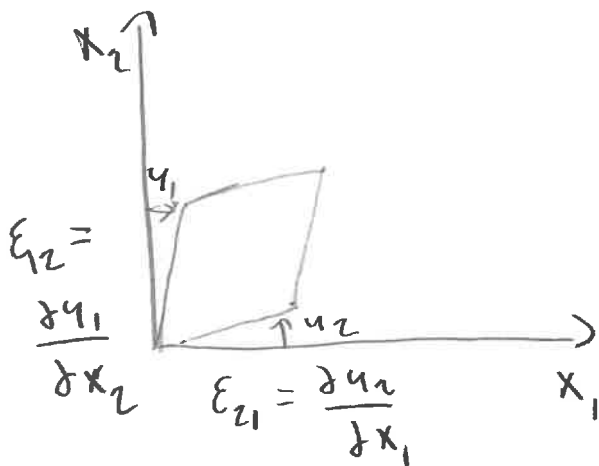
Total differential of displacement
 ➤ Cauchy strain tensor

$$du_i = \frac{\partial u_i}{\partial x_j} dx_j = \frac{\partial u_i}{\partial x_1} dx_1 + \frac{\partial u_i}{\partial x_2} dx_2 + \frac{\partial u_i}{\partial x_3} dx_3$$

$$du_i = \epsilon_{ij} dx_j$$

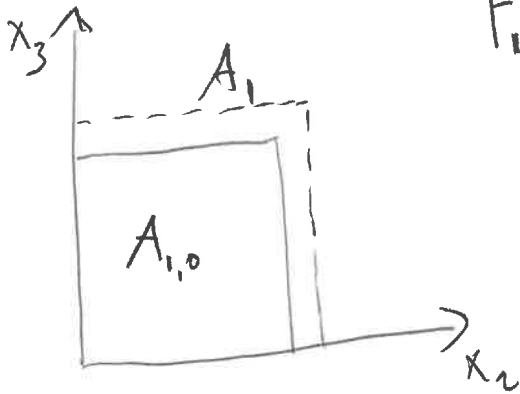
$$\begin{pmatrix} du_1 \\ du_2 \\ du_3 \end{pmatrix} = \begin{pmatrix} \epsilon_{11} & \epsilon_{12} & \epsilon_{13} \\ \epsilon_{21} & \epsilon_{22} & \epsilon_{23} \\ \epsilon_{31} & \epsilon_{32} & \epsilon_{33} \end{pmatrix} \begin{pmatrix} dx_1 \\ dx_2 \\ dx_3 \end{pmatrix}$$

Why is the strain tensor symmetric?



Force
Gross-sectional area
Engineering (nominal) stress

$$\sigma = \frac{F}{A_{\perp}}$$



$$F_i = F_{i,0} + \frac{\partial F_i}{\partial A_i} dA_i = F_{i,0} + \sigma_{ii} dA_i$$

$$= F_{i,0} + \sigma_{ii} (A_i - A_{i,0})$$

Total differential of Force:

$$dF_i = \frac{\partial F_i}{\partial A_j} dA_j = \frac{\partial F_i}{\partial A_1} dA_1 + \frac{\partial F_i}{\partial A_2} dA_2 + \frac{\partial F_i}{\partial A_3} dA_3$$

$$dF_i = \sigma_{ij} dA_j$$

$$\begin{pmatrix} dF_1 \\ dF_2 \\ dF_3 \end{pmatrix} = \begin{pmatrix} \sigma_{11} & \sigma_{12} & \sigma_{13} \\ \sigma_{21} & \sigma_{22} & \sigma_{23} \\ \sigma_{31} & \sigma_{32} & \sigma_{33} \end{pmatrix} \begin{pmatrix} dA_1 \\ dA_2 \\ dA_3 \end{pmatrix}$$

Why symmetric?

Total differential of strain
 → Compliance

$$d \epsilon_{ij} = \frac{\partial \epsilon_{ij}}{\partial \sigma_{kl}} d \sigma_{kl}$$

$$d \epsilon_{ij} = S_{ijkl} d \sigma_{kl}$$

$$\epsilon_{ij} = S_{ijkl} \sigma_{kl}$$

ϵ_{11}
 ϵ_{22}
 ϵ_{33}
 ϵ_{12}
 ϵ_{13}
 ϵ_{21}
 ϵ_{13}
 ϵ_{31}
 ϵ_{32}

S_{1111}	S_{1122}	S_{1133}	S_{1112}	S_{1113}	S_{1121}	S_{1123}	S_{1131}	S_{1132}
S_{2211}	S_{2222}	S_{2233}	S_{2212}	S_{2213}	S_{2221}	S_{2223}	S_{2231}	S_{2232}
S_{3311}	S_{3322}	S_{3333}	S_{3312}	S_{3313}	S_{3321}	S_{3323}	S_{3331}	S_{3332}
S_{1211}	S_{1222}	S_{1233}	S_{1212}	S_{1213}	S_{1221}	S_{1223}	S_{1231}	S_{1232}
S_{1311}	S_{1322}	S_{1333}	S_{1312}	S_{1313}	S_{1321}	S_{1323}	S_{1331}	S_{1332}
S_{2111}	S_{2122}	S_{2133}	S_{2112}	S_{2113}	S_{2121}	S_{2123}	S_{2131}	S_{2132}
S_{2311}	S_{2322}	S_{2333}	S_{2312}	S_{2313}	S_{2321}	S_{2323}	S_{2331}	S_{2332}
S_{3111}	S_{3122}	S_{3133}	S_{3112}	S_{3113}	S_{3121}	S_{3123}	S_{3131}	S_{3132}
S_{3211}	S_{3222}	S_{3233}	S_{3212}	S_{3213}	S_{3221}	S_{3223}	S_{3231}	S_{3232}

σ_{11}
 σ_{22}
 σ_{33}
 σ_{12}
 σ_{13}
 σ_{21}
 σ_{23}
 σ_{31}
 σ_{32}

Total differential of stress
 > Stiffness

$$d\sigma_{ij} = \frac{\partial \sigma_{ij}}{\partial \epsilon_{kl}} d\epsilon_{kl}$$

$$d\sigma_{ij} = Q_{ijkl} d\epsilon_{kl}$$

$$\sigma_{ij} = Q_{ijkl} \epsilon_{kl}$$

σ_{11} σ_{22} σ_{33} σ_{12} σ_{13} σ_{21} σ_{23} σ_{31} σ_{32}	=	<table border="0" style="width: 100%; text-align: center;"> <tr> <td>Q₁₁₁₁</td><td>Q₁₁₂₂</td><td>Q₁₁₃₃</td><td>Q₁₁₁₂</td><td>Q₁₁₁₃</td><td>Q₁₁₂₁</td><td>Q₁₁₂₃</td><td>Q₁₁₃₁</td><td>Q₁₁₃₂</td> </tr> <tr> <td>Q₂₂₁₁</td><td>Q₂₂₂₂</td><td>Q₂₂₃₃</td><td>Q₂₂₁₂</td><td>Q₂₂₁₃</td><td>Q₂₂₂₁</td><td>Q₂₂₂₃</td><td>Q₂₂₃₁</td><td>Q₂₂₃₂</td> </tr> <tr> <td>Q₃₃₁₁</td><td>Q₃₃₂₂</td><td>Q₃₃₃₃</td><td>Q₃₃₁₂</td><td>Q₃₃₁₃</td><td>Q₃₃₂₁</td><td>Q₃₃₂₃</td><td>Q₃₃₃₁</td><td>Q₃₃₃₂</td> </tr> <tr> <td>Q₁₂₁₁</td><td>Q₁₂₂₂</td><td>Q₁₂₃₃</td><td>Q₁₂₁₂</td><td>Q₁₂₁₃</td><td>Q₁₂₂₁</td><td>Q₁₂₂₃</td><td>Q₁₂₃₁</td><td>Q₁₂₃₂</td> </tr> <tr> <td>Q₁₃₁₁</td><td>Q₁₃₂₂</td><td>Q₁₃₃₃</td><td>Q₁₃₁₂</td><td>Q₁₃₁₃</td><td>Q₁₃₂₁</td><td>Q₁₃₂₃</td><td>Q₁₃₃₁</td><td>Q₁₃₃₂</td> </tr> <tr> <td>Q₂₁₁₁</td><td>Q₂₁₂₂</td><td>Q₂₁₃₃</td><td>Q₂₁₁₂</td><td>Q₂₁₁₃</td><td>Q₂₁₂₁</td><td>Q₂₁₂₃</td><td>Q₂₁₃₁</td><td>Q₂₁₃₂</td> </tr> <tr> <td>Q₂₃₁₁</td><td>Q₂₃₂₂</td><td>Q₂₃₃₃</td><td>Q₂₃₁₂</td><td>Q₂₃₁₃</td><td>Q₂₃₂₁</td><td>Q₂₃₂₃</td><td>Q₂₃₃₁</td><td>Q₂₃₃₂</td> </tr> <tr> <td>Q₃₁₁₁</td><td>Q₃₁₂₂</td><td>Q₃₁₃₃</td><td>Q₃₁₁₂</td><td>Q₃₁₁₃</td><td>Q₃₁₂₁</td><td>Q₃₁₂₃</td><td>Q₃₁₃₁</td><td>Q₃₁₃₂</td> </tr> <tr> <td>Q₃₂₁₁</td><td>Q₃₂₂₂</td><td>Q₃₂₃₃</td><td>Q₃₂₁₂</td><td>Q₃₂₁₃</td><td>Q₃₂₂₁</td><td>Q₃₂₂₃</td><td>Q₃₂₃₁</td><td>Q₃₂₃₂</td> </tr> </table>	Q ₁₁₁₁	Q ₁₁₂₂	Q ₁₁₃₃	Q ₁₁₁₂	Q ₁₁₁₃	Q ₁₁₂₁	Q ₁₁₂₃	Q ₁₁₃₁	Q ₁₁₃₂	Q ₂₂₁₁	Q ₂₂₂₂	Q ₂₂₃₃	Q ₂₂₁₂	Q ₂₂₁₃	Q ₂₂₂₁	Q ₂₂₂₃	Q ₂₂₃₁	Q ₂₂₃₂	Q ₃₃₁₁	Q ₃₃₂₂	Q ₃₃₃₃	Q ₃₃₁₂	Q ₃₃₁₃	Q ₃₃₂₁	Q ₃₃₂₃	Q ₃₃₃₁	Q ₃₃₃₂	Q ₁₂₁₁	Q ₁₂₂₂	Q ₁₂₃₃	Q ₁₂₁₂	Q ₁₂₁₃	Q ₁₂₂₁	Q ₁₂₂₃	Q ₁₂₃₁	Q ₁₂₃₂	Q ₁₃₁₁	Q ₁₃₂₂	Q ₁₃₃₃	Q ₁₃₁₂	Q ₁₃₁₃	Q ₁₃₂₁	Q ₁₃₂₃	Q ₁₃₃₁	Q ₁₃₃₂	Q ₂₁₁₁	Q ₂₁₂₂	Q ₂₁₃₃	Q ₂₁₁₂	Q ₂₁₁₃	Q ₂₁₂₁	Q ₂₁₂₃	Q ₂₁₃₁	Q ₂₁₃₂	Q ₂₃₁₁	Q ₂₃₂₂	Q ₂₃₃₃	Q ₂₃₁₂	Q ₂₃₁₃	Q ₂₃₂₁	Q ₂₃₂₃	Q ₂₃₃₁	Q ₂₃₃₂	Q ₃₁₁₁	Q ₃₁₂₂	Q ₃₁₃₃	Q ₃₁₁₂	Q ₃₁₁₃	Q ₃₁₂₁	Q ₃₁₂₃	Q ₃₁₃₁	Q ₃₁₃₂	Q ₃₂₁₁	Q ₃₂₂₂	Q ₃₂₃₃	Q ₃₂₁₂	Q ₃₂₁₃	Q ₃₂₂₁	Q ₃₂₂₃	Q ₃₂₃₁	Q ₃₂₃₂	ϵ_{11} ϵ_{22} ϵ_{33} ϵ_{12} ϵ_{13} ϵ_{21} ϵ_{23} ϵ_{31} ϵ_{32}
Q ₁₁₁₁	Q ₁₁₂₂	Q ₁₁₃₃	Q ₁₁₁₂	Q ₁₁₁₃	Q ₁₁₂₁	Q ₁₁₂₃	Q ₁₁₃₁	Q ₁₁₃₂																																																																												
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Now, stress and strain tensors are symmetric -> six independent components.

Is it possible to reduce the 9*9 matrices into 6*6?

Indeed...

ϵ_{11}	S_{1111}	S_{1122}	S_{1133}	$2 S_{1112}$	$2 S_{1113}$	$2 S_{1123}$	σ_{11}
ϵ_{22}	S_{2211}	S_{2222}	S_{2233}	$2 S_{2212}$	$2 S_{2213}$	$2 S_{2223}$	σ_{22}
ϵ_{33}	S_{3311}	S_{3322}	S_{3333}	$2 S_{3312}$	$2 S_{3313}$	$2 S_{3323}$	σ_{33}
$2 \epsilon_{12}$	$2 S_{1211}$	$2 S_{1222}$	$2 S_{1233}$	$4 S_{1212}$	$4 S_{1213}$	$4 S_{1223}$	σ_{12}
$2 \epsilon_{13}$	$2 S_{1311}$	$2 S_{1322}$	$2 S_{1333}$	$4 S_{1312}$	$4 S_{1313}$	$4 S_{1323}$	σ_{13}
$2 \epsilon_{23}$	$2 S_{2311}$	$2 S_{2322}$	$2 S_{2333}$	$4 S_{2312}$	$4 S_{2313}$	$4 S_{2323}$	σ_{23}

σ_{11}	Q_{1111}	Q_{1122}	Q_{1133}	Q_{1112}	Q_{1113}	Q_{1123}	ϵ_{11}
σ_{22}	Q_{2211}	Q_{2222}	Q_{2233}	Q_{2212}	Q_{2213}	Q_{2223}	ϵ_{22}
σ_{33}	Q_{3311}	Q_{3322}	Q_{3333}	Q_{3312}	Q_{3313}	Q_{3323}	ϵ_{33}
σ_{12}	Q_{1211}	Q_{1222}	Q_{1233}	Q_{1212}	Q_{1213}	Q_{1223}	$2 \epsilon_{12}$
σ_{13}	Q_{1311}	Q_{1322}	Q_{1333}	Q_{1312}	Q_{1313}	Q_{1323}	$2 \epsilon_{13}$
σ_{23}	Q_{2311}	Q_{2322}	Q_{2333}	Q_{2312}	Q_{2313}	Q_{2323}	$2 \epsilon_{23}$

Symmetry of Compliance and Stiffness

Strain energy density $\hat{w} = \frac{1}{2} \epsilon_{ij}' \sigma_{ij}'$

$$\frac{\partial \hat{w}}{\partial \epsilon_{ij}} = \sigma_{ij}' \quad \frac{\partial \hat{w}}{\partial \sigma_{ij}'} = \epsilon_{ij}'$$

on the other hand

$$\hat{w} = \frac{1}{2} (S_{ijkl} \sigma_{kl}) \sigma_{ij}'$$

$$\begin{aligned} \frac{\partial \hat{w}}{\partial \sigma_{mn}} &= \frac{1}{2} S_{mnkl} \sigma_{kl} + \frac{1}{2} S_{ijmn} \sigma_{ij}' \\ &= \frac{1}{2} (S_{mnij} + S_{ijmn}) \sigma_{ij}' \end{aligned}$$

but $\epsilon_{mn} = S_{mnij} \sigma_{ij}'$

$$\frac{1}{2} (S_{mnij} + S_{ijmn}) = S_{mnij}'$$

$$\Rightarrow S_{mnij} = S_{ijmn}$$

$$\frac{1}{2}(a+b) = a$$

$$\frac{1}{2}b = \frac{1}{2}a$$

Similarly for stiffness:

$$\hat{w} = \frac{1}{2} \epsilon_{ij}' (Q_{ijkl} \epsilon_{kl})$$

$$\begin{aligned} \frac{\partial \hat{w}}{\partial \epsilon_{mn}} &= \frac{1}{2} Q_{mnkl} \epsilon_{kl} + \frac{1}{2} Q_{ijmn} \epsilon_{ij}' = \frac{1}{2} (Q_{mnij} + Q_{ijmn}) \epsilon_{mn} \\ &= \sigma_{mn} = Q_{mnij}' \epsilon_{ij}' \end{aligned}$$

$$\Rightarrow Q_{mnij} = Q_{ijmn} \quad \Rightarrow 95 \text{ independent components}$$

Further symmetries of Compliance and Stiffness

Due to symmetry of the strain tensor:

$$Q_{ijkl} = Q_{ijlk}$$

$$S_{ijkl} = S_{jikl}$$

Due to symmetry of the stress tensor:

$$Q_{ijkl} = Q_{jikl}$$

$$S_{ijkl} = S_{ijlk}$$

Combining both symmetries:

$$Q_{ijkl} = Q_{jilk}$$

$$S_{ijkl} = S_{ijlk}$$

⇒ Matrices can be written as 6*6 square matrices

$$\sigma_{ij} = \sigma_{ji}$$

Engineering shear strain $e_{ij} = \varepsilon_{ij} + \varepsilon_{ji} = 2\varepsilon_{ij}$

Symmetry -> 21 independent components

Orthotropic material symmetry

Orthotropic Material, on-axis co-ordinates

- 2 perpendicular lines of reflection symmetry (2d)
- 3 perpendicular planes of reflection symmetry (3d)

- Shear stresses are not linked to normal strains
- Normal stresses are not linked to shear strains

- Shear strains are not linked to normal stresses
- Normal strains are not linked to shear stresses

Why are shear stresses not linked to normal strains, etc?

Any reflections wrt a symmetry plane changes the sign of one co-ordinate (or displacement)

=> Normal strains and stresses invariant in symmetry transformations

=> Shear strains and stresses change sign in symmetry transformations

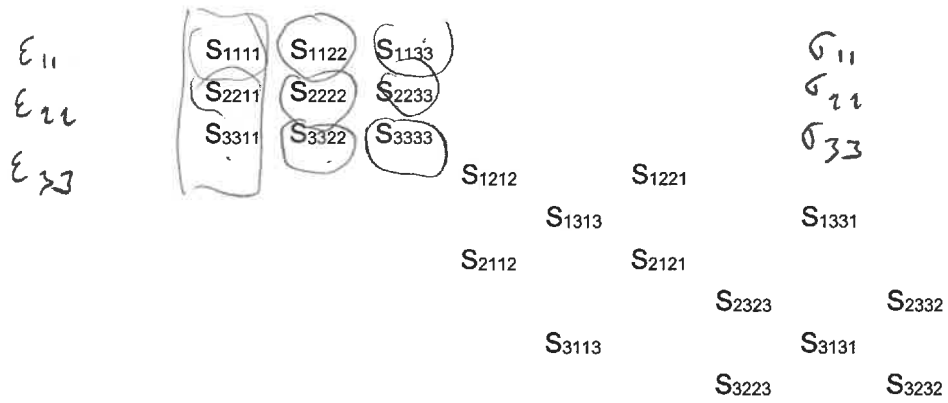
=> Stiffnesses and compliances linking shear and normal strains/stresses should change sign in symmetry transformations. The only constant being equal to its negative is zero – this of course applies also to material constants!

Orthotropic Material, continued

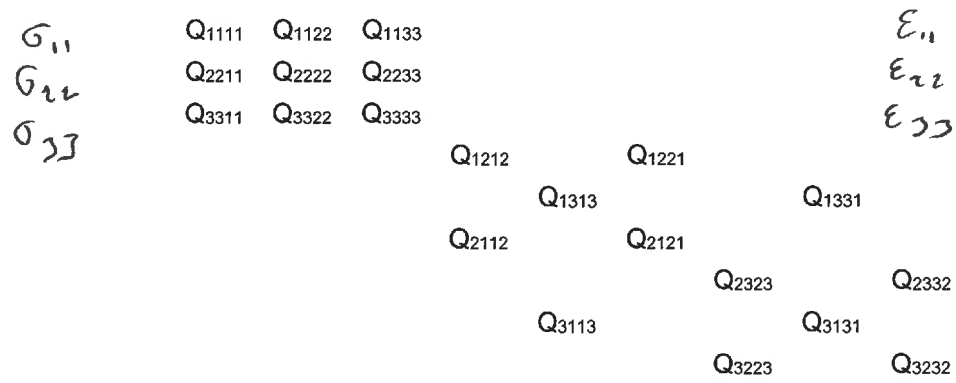
Why are shear stresses σ_{ij} not linked to shear strains σ_{jk} ?

Reflection wrt symmetry plane (j,k) changes the sign of the co-ordinate (or displacement) i. Thus σ_{ij} changes sign, but σ_{jk} does not. The only material constant equal to its negative is again zero...

Compliance Matrix – 9 independent components



Stiffness Matrix – 9 independent components



Co-ordinate transformations of Strain, Stress, Compliance and Stiffness

Off-axis mechanical behavior of orthotropic materials

Off-axis stresses known – determine off-axis strains

1/ Stress transformation to on-axis

$$\bar{\sigma} = T \bar{\sigma}'$$

2/ Use on-axis compliance matrix to determine on-axis strains

$$\bar{\varepsilon} = S \bar{\sigma}$$

3/ Negative transformation of strain to off-axis

$$\bar{\varepsilon}' = K^{-1} \bar{\varepsilon}$$

Off-axis strains known – determine off-axis stresses

1/ Strain transformation to on-axis

$$\bar{\varepsilon}' = K \bar{\varepsilon} \quad \bar{\varepsilon} = K^{-1} \bar{\varepsilon}'$$

2/ Use on-axis stiffness matrix to determine on-axis stresses

$$\bar{\sigma} = Q \bar{\varepsilon}$$

3/ Negative transformation of stress to off-axis

$$\bar{\sigma}' = T^{-1} \bar{\sigma}$$

This cannot be done using the Engineering constants!

Co-ordinate transformation of Compliance

- | | |
|--|--|
| 1/ Transform stress to on-axis | $\bar{\sigma} = T \bar{\sigma}'$ |
| 2/ Use on-axis compliance to compute strain | $\bar{\varepsilon} = S \bar{\sigma}$ |
| 3/ Transform strain to off-axis | $\bar{\varepsilon}' = K^{-1} \bar{\varepsilon}$ |
| 4/ Identify off-axis Compliance components – they are given as polynomials of on-axis compliance components! | $\bar{\varepsilon}' = K^{-1} S T \bar{\sigma}' = S' \bar{\sigma}'$ |

Co-ordinate transformation of Stiffness

- | | | |
|--|---|--|
| 1/ Transform strain to on-axis | $\bar{\varepsilon}' = K \bar{\varepsilon}$ | $\bar{\varepsilon} = \bar{K} \bar{\varepsilon}'$ |
| 2/ Use on-axis stiffness to compute stress | $\bar{\sigma} = Q \bar{\varepsilon}$ | |
| 3/ Transform stress to off-axis | $\bar{\sigma}' = T^{-1} \bar{\sigma}$ | |
| 4/ Identify off-axis Stiffness components – they are given as polynomials of on-axis stiffness components! | $\bar{\sigma}' = T^{-1} Q K \bar{\varepsilon}' = Q' \bar{\varepsilon}'$ | |

How do we determine Compliance Matrix experimentally?

Once we know Compliance Matrix, how do we get to know Stiffness Matrix?

If we know Stiffness Matrix, how do we get to know Compliance Matrix?

S_{1111}	S_{1122}	S_{1133}			
S_{2211}	S_{2222}	S_{2233}			
S_{3311}	S_{3322}	S_{3333}			
			S_{1212}	S_{1221}	
			S_{1313}		S_{1331}
			S_{2112}	S_{2121}	
					S_{2323}
			S_{3113}		S_{3131}
				S_{3223}	S_{3232}

Q_{1111}	Q_{1122}	Q_{1133}			
Q_{2211}	Q_{2222}	Q_{2233}			
Q_{3311}	Q_{3322}	Q_{3333}			
			Q_{1212}	Q_{1221}	
			Q_{1313}		Q_{1331}
			Q_{2112}	Q_{2121}	
					Q_{2323}
			Q_{3113}		Q_{3131}
				Q_{3223}	Q_{3232}

How do we invert a matrix?

- Gaussian Elimination
- Cramer's Rule (cofactors)
- Cholensky Decomposition
- Eigendecomposition
- Cayley-Hamilton

II Newtonian flow

Newtonian Viscosity

Interaction of molecules -> internal fluid friction

$$\bar{\sigma} = Q \bar{\varepsilon}$$

$$\rightarrow \sigma_{ij} = \mu \varepsilon_{ij} = \mu \frac{\partial \varepsilon_{ij}}{\partial t} = \mu \frac{\partial^2 u_i}{\partial t \partial x_j}$$

Gravity Drainage Experiment

$$dV_1 = -dV_2$$

$$\Delta p = p_2 - p_1$$



Darcy's Law

$$\frac{dV}{dt} \propto \Delta p$$

$$\frac{dV_1}{dt} = \frac{\Delta p A}{\mu R}$$

$$\frac{dV_2}{dt} = -\frac{\Delta p A}{\mu R} = -\frac{\Delta p A}{\mu b SFR}$$

$$\frac{dV_2}{A dt} = -\frac{\Delta p}{\mu b SFR} \rightarrow -\frac{K dp}{\mu dx}$$

Flux Equation

1-d Fick's law

$$\frac{\partial^2 \Omega}{\partial t \partial A} = -D \frac{\partial^2 \Omega}{\partial x \partial V}$$

3-d Fick's law

$$\bar{J} = -[D] \nabla \theta$$

or

$$J_i = \frac{\partial^2 \Omega}{\partial t \partial A_i} = -D_{ij} \frac{\partial^2 \Omega}{\partial x_j \partial V}$$

Hagen-Poiseuille Law

$$-(p_2 - p_1)\pi r^2 + \sigma_{lr} 2\pi r \Delta l = 0$$

$$-(p_2 - p_1)\pi r^2 + \mu \varepsilon_{lr} 2\pi r \Delta l = 0$$

$$\varepsilon_{lr} = \frac{d}{dt} \frac{du}{dr} = \frac{d}{dr} \frac{du}{dt} = \frac{d}{dr} v$$

$$\varepsilon_{lr} = \frac{(p_2 - p_1)r}{2\mu \Delta l} \approx \frac{dp}{dl} \frac{r}{2\mu}$$

$$\frac{dv}{dr} = \frac{dp}{dl} \frac{r}{2\mu}$$

$$dv = \frac{dp}{dl} \frac{r}{2\mu} dr$$

$$v = \frac{dp}{dl} \frac{r^2}{4\mu} + C$$

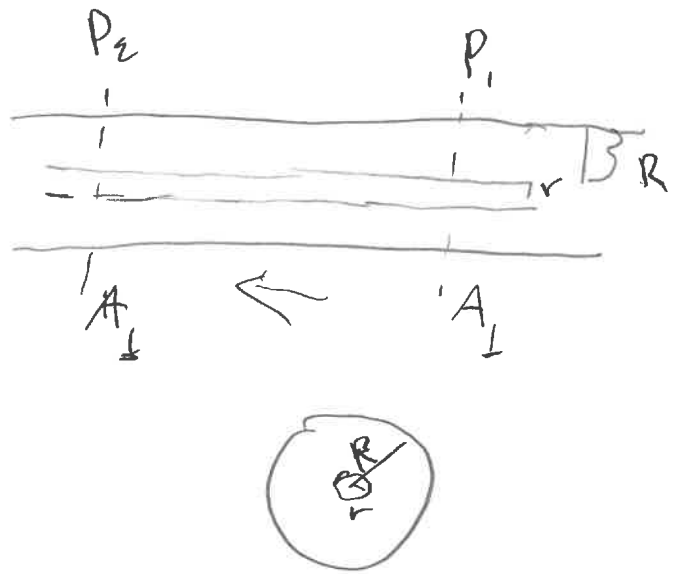
$$v(r=R) = 0 \rightarrow C = -\frac{dp}{dl} \frac{R^2}{4\mu}$$

$$v(r) = \frac{dp}{dl} \frac{r^2 - R^2}{4\mu}$$

$$\frac{dV}{dt} = \int_0^R 2\pi r v(r) dr = -\frac{dp}{dl} \frac{\pi}{2\mu} \int_0^R (r R^2 - r^3) dr = -\frac{dp}{dl} \frac{\pi}{2\mu} \int_0^R (r R^2 - r^3) dr = -\frac{dp}{dl} \frac{\pi R^4}{8\mu}$$

Flux

$$\frac{dV}{A_{\perp} dt} = -\frac{dp}{\pi R^2 dl} \frac{\pi R^4}{8\mu} = -\frac{dp}{dl} \frac{R^2}{8\mu}$$



$$\int_0^R \frac{r^2 R^2}{2} - \frac{r^4}{4}$$

$$\frac{R^4}{2} - \frac{R^4}{4} = \frac{R^4}{4}$$

Poros System Consisting of Parallel Tubes

$$\frac{dV}{dt} = \left(\frac{dV}{dt}\right)_1 + \left(\frac{dV}{dt}\right)_2 + \dots + \left(\frac{dV}{dt}\right)_n$$

$$\frac{dV}{A_{\perp} dt} = \frac{1}{A_{\perp}} \left[\left(\frac{dV}{dt}\right)_1 + \left(\frac{dV}{dt}\right)_2 + \dots + \left(\frac{dV}{dt}\right)_n \right]$$

$$\frac{dV}{A_{\perp} dt} = \frac{1}{A_{\perp}} \left[A_1 \left(\frac{dV}{A dt}\right)_1 + A_2 \left(\frac{dV}{A dt}\right)_2 + \dots + A_n \left(\frac{dV}{A dt}\right)_n \right]$$

If all tubes are of the same size

$$\frac{dV}{A_{\perp} dt} = \frac{n A_1}{A_{\perp}} \left(\frac{dV}{A dt}\right)_1 = \frac{n A_1}{A_{\perp}} \left(-\frac{dp}{dl} \frac{R^2}{8\mu}\right) = P \left(-\frac{dp}{dl} \frac{R^2}{8\mu}\right)$$

If all tubes are not of the same size

$$\begin{aligned} \frac{dV}{A_{\perp} dt} &= \frac{A_1}{A_{\perp}} \left(-\frac{dp}{dl} \frac{R_1^2}{8\mu}\right) + \frac{A_2}{A_{\perp}} \left(-\frac{dp}{dl} \frac{R_2^2}{8\mu}\right) + \dots + \frac{A_n}{A_{\perp}} \left(-\frac{dp}{dl} \frac{R_n^2}{8\mu}\right) \\ &= -\frac{1}{A_{\perp}} \frac{dp}{dl} \frac{1}{8\mu} (A_1 R_1^2 + A_2 R_2^2 + \dots + A_n R_n^2) \\ &= -\frac{A_p}{A_{\perp}} \frac{dp}{dl} \frac{1}{8\mu} \frac{A_1 R_1^2 + A_2 R_2^2 + \dots + A_n R_n^2}{A_p} \end{aligned}$$

In the continuum form

$$\begin{aligned} \frac{dV}{A_{\perp} dt} &= -P \frac{dp}{dl} \frac{1}{8\mu} \int p(A) R^2 dA \\ &= -P \frac{dp}{dl} \frac{1}{8\mu} \int p(A) R^2 2\pi R dR \\ &= -P \frac{dp}{dl} \frac{1}{8\mu} \int p(R) R^2 dR \end{aligned}$$

$$\int p(A) dA = 1$$

$$\int p(A) d(\pi R^2) = 1$$

$$\frac{d \pi R^2}{d R} = 2 \pi R$$

$$d \pi R^2 = 2\pi R d R$$

$$\int p(A) 2\pi R d R = 1$$

$$p(R) = p(A) 2\pi R$$

Recall Darcy's Law - Flux Equation

$$\frac{dV}{dt} \propto \Delta p$$

$$\frac{d^2V}{dA_{\perp} dt} = -\frac{\Delta p}{\mu b SFR} \rightarrow -\frac{K dp}{\mu dx}$$

Porosity effect

$$\frac{d}{dA_{\perp}} \frac{dV}{dt} = \frac{dN_p}{dA_{\perp}} \frac{d}{dN_p} \frac{dV}{dt}$$

$$P = \frac{dA_p}{dA_{\perp}} = \frac{dN_p A_i}{dA_{\perp}} \Rightarrow \frac{dN_p}{dA_{\perp}} = \frac{P}{A_i}$$

$$\frac{d}{dN} \frac{dV}{dt} = \left(\frac{dV}{dt} \right)_1 = -\frac{dp \pi R^4}{dl 8\mu}$$

Flux within a porous body

$$\frac{d}{dA_{\perp}} \frac{dV}{dt} = \frac{dN_p}{dA_{\perp}} \frac{d}{dN_p} \frac{dV}{dt} = \frac{P}{\pi R^2} \left(-\frac{dp \pi R^4}{dl 8\mu} \right) = P \left(-\frac{dp R^2}{dl 8\mu} \right)$$

$$\Rightarrow K = P \frac{R^2}{8}$$

Variable size of pores

$$\Rightarrow K = \frac{P}{8} \int R^2 p(R) dR$$

III Diffusion

$$\bar{a} = a_1 \hat{e}_1 + a_2 \hat{e}_2 + a_3 \hat{e}_3$$

$$\nabla = \hat{e}_1 \frac{\partial}{\partial x_1} + \hat{e}_2 \frac{\partial}{\partial x_2} + \hat{e}_3 \frac{\partial}{\partial x_3}$$

Divergence Theorem

$$\int_V \nabla \cdot \bar{a} dV = \oint_S \bar{a} \cdot d\bar{s} \quad \nabla = \hat{e}_i \frac{\partial}{\partial x_i} \quad \nabla \cdot \bar{a} = \frac{\partial a_1}{\partial x_1} + \frac{\partial a_2}{\partial x_2} + \frac{\partial a_3}{\partial x_3}$$

Total flow rate out of volume V



$$-\frac{dQ}{dt} = \oint_S \bar{J} \cdot d\bar{s} = \oint_S -D \nabla \phi \cdot d\bar{s}$$

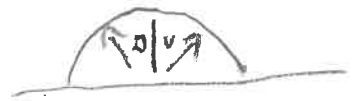
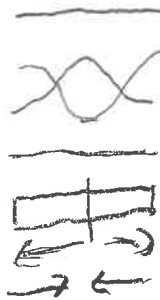
$$-\frac{dQ}{dt} = \oint_S \bar{J} \cdot d\bar{s} = \int_V \nabla \cdot \bar{J} dV = \int_V -D \nabla^2 \phi dV$$

$$Q = \int_V \phi dV$$

$$-\frac{dQ}{dt} = -\int_V \frac{\partial \phi}{\partial t} dV$$

$$\frac{\partial \phi}{\partial t} = D \nabla^2 \phi$$

Diffusion Equation



$$\frac{\partial \phi}{\partial t} + \nabla \cdot \bar{J} = 0$$

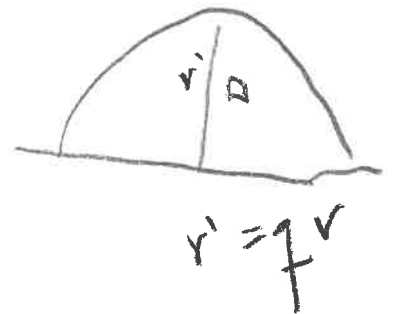
Continuity Equation

$$\frac{\partial J}{\partial x} = 0 \Rightarrow J = C \quad \frac{d(\text{constant})}{dx} = 0$$

Thermal Flux Equation

$$\bar{J} = -D \nabla \phi \quad \text{or} \quad \frac{\partial^2 Q}{\partial A_j \partial t} \hat{e}_j = -\delta_{ijk} D_i \hat{e}_i \frac{\partial^2 Q}{\partial x_k \partial V} \rightarrow \text{20b}$$

$$\left[\frac{J}{s m^2} \right] = \left[\frac{m^2}{s} \right] \left[\frac{J}{m^4} \right]$$



Thermal Conductivity Equation

$$\bar{J} = -D \nabla \phi \quad \text{or} \quad \frac{\partial^2 Q}{\partial A_j \partial t} \hat{e}_j = -\delta_{ijk} \kappa_i \hat{e}_i \frac{\partial T}{\partial x_k} \rightarrow \text{20b}$$

$$\left[\frac{J}{s m^2} \right] = \left[\frac{J}{m s K} \right] \left[\frac{K}{m} \right]$$

$$\kappa = D \frac{\partial^2 Q}{\partial T \partial V} \rightarrow \text{20b} \quad \text{Thermal conductivity}$$

$$\frac{\partial^2 Q}{\partial T \partial V} \quad \text{Volumetric heat capacity}$$

III Diffusion

Divergence Theorem

$$\int_V \nabla \cdot \bar{a} \, dV = \oint_s \bar{a} \cdot d\bar{s} \quad \nabla = \hat{e}_i \frac{\partial}{\partial x_i} \quad \nabla \cdot \bar{a} = \frac{\partial a_1}{\partial x_1} + \frac{\partial a_2}{\partial x_2} + \frac{\partial a_3}{\partial x_3}$$

Total flow rate out of volume V

$$-\frac{dQ}{dt} = \oint_s \bar{J} \cdot d\bar{s} = \oint_s -D \nabla \phi \cdot d\bar{s}$$

$$-\frac{dQ}{dt} = \oint_s \bar{J} \cdot d\bar{s} = \int_V \nabla \cdot \bar{J} \, dV = \int_V -D \nabla^2 \phi \, dV$$

$$Q = \int_V \phi \, dV$$

$$-\frac{dQ}{dt} = -\int_V \frac{\partial \phi}{\partial t} \, dV$$

$$\frac{\partial \phi}{\partial t} = D \nabla^2 \phi \quad \text{Diffusion Equation}$$

$$\frac{\partial \phi}{\partial t} + \nabla \cdot \bar{J} = 0 \quad \text{Continuity Equation}$$

Thermal Flux Equation

$$\bar{J} = -D \nabla \phi \quad \text{or} \quad \frac{\partial^2 Q}{\partial A_i \partial t} = -D_{ij} \frac{\partial^2 Q}{\partial x_j \partial V}$$

$$\left[\frac{J}{s \, m^2} \right] = \left[\frac{m^2}{s} \right] \left[\frac{J}{m^4} \right]$$

Thermal Conductivity Equation

$$\bar{J} = -D \nabla \phi \quad \text{or} \quad \frac{\partial^2 Q}{\partial A_i \partial t} = -\kappa_{ij} \frac{\partial T}{\partial x_j}$$

$$\left[\frac{J}{s \, m^2} \right] = \left[\frac{J}{m \, s \, K} \right] \left[\frac{K}{m} \right]$$

$$\kappa_{ij} = D_{ij} \frac{\partial^2 Q}{\partial T \partial V} \quad \text{Thermal conductivity}$$

$$\frac{\partial^2 Q}{\partial T \partial V} \quad \text{Volumetric heat capacity}$$

How to use the Diffusion Equation?

Can we use the Diffusion Equation without solving it?

$$\frac{\partial \phi}{\partial t} = D \nabla^2 \phi \quad \text{Diffusion Equation}$$

$$\frac{\partial \phi}{\partial t} = \sum_{i=1}^3 D_{ij} \frac{\partial^2 \phi}{\partial x_j^2}$$

Introduce linear size scaling with scaling factor qt

$$\frac{\partial \phi}{\partial q^n t} = \sum_{i=1}^3 D_{ij} \frac{\partial^2 \phi}{\partial (qx_k)^2} \quad \Rightarrow n=2$$

An application to drying, impregnation, or heating time:

$$\Delta t = \int_{\phi_o}^{\phi_f} \frac{\partial t}{\partial \phi} d\phi$$

$$\Delta t' = \int_{\phi_o}^{\phi_f} q^2 \frac{\partial t}{\partial \phi} d\phi = q^2 \Delta t$$

How to solve the Diffusion Equation?

Steady-state problems:

$$\frac{\partial \phi}{\partial t} = 0 \quad \Rightarrow \quad 0 = \nabla^2 \phi \quad \text{Laplace Eq.}$$

Transient problems:

Fourier Series Solution

Example:

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2}$$

Wall of thickness L

Heater, Power/area=H

$$\text{Flux at heat source } J(L, t) = -D \frac{\partial u}{\partial x} = -H \quad \text{Inhomogeneous boundary condition}$$

$$\text{Outside generalized temperature } u(0, t) = 0$$

$$\text{Initial generalized temperature } u(x, 0) = 0$$

Potential function transformation $u(x, t) = v(x, t) + w(x)$

$$\frac{\partial w}{\partial t} = D \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 v}{\partial x^2} \right)$$

$$\text{Outside generalized temperature } v(0, t) + w(0) = 0$$

$$\text{Initial generalized temperature } v(x, 0) + w(x) = 0$$

$$\text{Flux at heat source } J(L, t) = -D \left[\frac{\partial v(L, t)}{\partial x} + \frac{\partial w(L, t)}{\partial x} \right] = -H \Rightarrow$$

$$\left[\frac{\partial v(L, t)}{\partial x} + \frac{\partial w(L, t)}{\partial x} \right] = \frac{H}{D}$$

Set $w = \frac{Hx}{D}$, then

$$\frac{\partial v(L, t)}{\partial x} = 0 \quad \text{Homogeneous boundary condition}$$

$$\frac{\partial v(x, 0)}{\partial x} = -\frac{H}{D} \Rightarrow v(x, 0) = -\frac{Hx}{D}$$

$$v(0, t) = 0$$

Let us try to solve $v(x, t)$ by separation of variables:

$$v(x, t) = X(x)T(t)$$

$$\frac{\partial [X(x)T(t)]}{\partial t} = D \frac{\partial^2 [X(x)T(t)]}{\partial x^2}$$

$$X T' = D X'' T$$

$$\frac{X''}{X} = \frac{1}{D} \frac{T'}{T} \equiv -\lambda^2$$

$$X'' = -\lambda^2 X$$

$$X = a e^{i\lambda x} + b e^{-i\lambda x} = A \cos(\lambda x) + B \sin(\lambda x)$$

$$T' = -\lambda^2 D T$$

$$T = c e^{-\lambda^2 D t}$$

$$v(x, t) = [A \cos(\lambda x) + B \sin(\lambda x)] e^{-\lambda^2 D t}$$

Boundary conditions:

$$v(0, t) = 0 \Rightarrow A = 0$$

$$\frac{\partial v(L, t)}{\partial x} = 0 \Rightarrow \lambda = \frac{n \pi}{2L}, \quad n = 1, 3, 5, 7, \dots$$

One solution:

$$v(x, t) = B \sin\left(\frac{n \pi}{2L} x\right) e^{-\frac{n^2 \pi^2 D}{4L^2} t}$$

General solution as superposition

$$v(x, t) = \sum_{n \text{ odd}} B_n \sin\left(\frac{n \pi}{2L} x\right) e^{-\frac{n^2 \pi^2 D}{4L^2} t}$$

With boundary condition $t=0$

$$v(x, 0) = \sum_{n \text{ odd}} B_n \sin\left(\frac{n \pi}{2L} x\right) = -\frac{H x}{D} \quad \text{Identify Fourier sine series}$$

$$v(x,0) = \sum_{n \text{ odd}} B_n \sin\left(\frac{n \pi}{2L} x\right) = -\frac{H x}{D}$$

$$\cdot \sin\left(\frac{n \pi}{2L} x\right)$$

$$\int_{-L}^L dx$$

$$\int_b^{b+\pi} \sin^2(x) dx = \frac{\pi}{2}$$

$$\frac{2L}{2} B_n = \int_{-L}^L -\frac{H x}{D} \sin\left(\frac{n \pi}{2L} x\right) dx$$

$$B_n = -\frac{H}{LD} \int_{-L}^L x \sin\left(\frac{n \pi}{2L} x\right) dx$$

$$= -\frac{H}{D} \frac{4L}{n^2 \pi^2} \int_{\frac{-n\pi}{2}}^{\frac{n\pi}{2}} \frac{n \pi x}{2L} \sin\left(\frac{n \pi}{2L} x\right) d \frac{n \pi x}{2L}$$

$$= -\frac{H}{D} \frac{8L}{n^2 \pi^2} \int_0^{\frac{n\pi}{2}} y \sin(y) dy$$

$$= -\frac{H}{D} \frac{8L}{n^2 \pi^2} \int_0^{\frac{n\pi}{2}} y \sin(y) dy$$

$$= -\frac{H}{D} \frac{8L}{n^2 \pi^2} \left\{ \frac{n\pi}{2} \left| y [-\cos(y)] - \int_0^{\frac{n\pi}{2}} -\cos(y) dy \right. \right\}$$

$$= -\frac{H}{D} \frac{8L}{n^2 \pi^2} \frac{n\pi}{2} \left| \sin(y) \right| = -\frac{H}{D} \frac{8L}{\pi^2} \frac{(-1)^{\frac{n-1}{2}}}{n^2}$$

$$v(x,0) = -\frac{H}{D} \frac{8L}{\pi^2} \sum_{n \text{ odd}} \frac{(-1)^{\frac{n-1}{2}}}{n^2} \sin\left(\frac{n \pi}{2L} x\right)$$

$$u(x,t) = w(x) + v(x,t)$$

$$= \frac{H}{D} x - \frac{H}{D} \frac{8L}{\pi^2} \sum_{n \text{ odd}} \frac{(-1)^{\frac{n-1}{2}}}{n^2} \sin\left(\frac{n \pi}{2L} x\right) e^{-\frac{n^2 \pi^2 D}{4L^2} t}$$

Potential function in terms of reduced variables:

$$u' = u \frac{H}{LD} \quad \text{Reduced heat density}$$

$$x' = \frac{x}{L} \quad \text{Reduced position}$$

$$t' = \frac{\pi^2 D}{4L^2} t \quad \text{Reduced time}$$

$$u'(x', t') = x' - \frac{8}{\pi^2} \sum_{n \text{ odd}} \frac{(-1)^{\frac{n-1}{2}}}{n^2} \sin\left(\frac{n \pi}{2} x'\right) e^{-n^2 t'}$$

Does the solution satisfy the Diffusion Equation $\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2}$?

$$w(x) = \frac{Hx}{D}$$

$$\frac{\partial^2 w}{\partial x^2} = 0 \Rightarrow \frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial v}{\partial x} = -\frac{H}{D} \frac{8L}{\pi^2} \sum_{n \text{ odd}} \frac{n \pi}{2L} \frac{(-1)^{\frac{n-1}{2}}}{n^2} \cos\left(\frac{n \pi}{2L} x\right) e^{-\frac{n^2 \pi^2 D}{4L^2} t}$$

$$\frac{\partial^2 v}{\partial x^2} = \frac{H}{D} \frac{8L}{\pi^2} \sum_{n \text{ odd}} \frac{n^2 \pi^2}{4L^2} \frac{(-1)^{\frac{n-1}{2}}}{n^2} \sin\left(\frac{n \pi}{2L} x\right) e^{-\frac{n^2 \pi^2 D}{4L^2} t}$$

$$= \frac{H}{LD} \frac{2}{\pi^2} \sum_{n \text{ odd}} \frac{(-1)^{\frac{n-1}{2}}}{n^2} \sin\left(\frac{n \pi}{2L} x\right) e^{-\frac{n^2 \pi^2 D}{4L^2} t}$$

$$\frac{\partial v}{\partial t} = \frac{H}{D} \frac{8L}{\pi^2} \sum_{n \text{ odd}} \frac{n^2 \pi^2 D}{4L^2} \frac{(-1)^{\frac{n-1}{2}}}{n^2} \sin\left(\frac{n \pi}{2L} x\right) e^{-\frac{n^2 \pi^2 D}{4L^2} t}$$

$$= \frac{H}{L} \frac{2}{\pi^2} \sum_{n \text{ odd}} \frac{(-1)^{\frac{n-1}{2}}}{n^2} \sin\left(\frac{n \pi}{2L} x\right) e^{-\frac{n^2 \pi^2 D}{4L^2} t}$$

$$\frac{\partial v}{\partial t} = D \frac{\partial^2 v}{\partial x^2} \quad \text{PROVEN}$$

How does the solution become in other problems?

One-dimensional symmetric drying/impregnation problem

Again:

$$\frac{\partial u}{\partial t} = D \frac{\partial^2 u}{\partial x^2}$$

$$u(x, t) = X(x)T(t)$$

$$X T' = D X'' T$$

$$\frac{X''}{X} = \frac{1}{D} \frac{T'}{T} \equiv -\lambda^2$$

$$X'' = -\lambda^2 X$$

$$X = a e^{i\lambda x} + b e^{-i\lambda x} = A \cos(\lambda x) + B \sin(\lambda x)$$

$$T' = -\lambda^2 D T$$

$$T = c e^{-\lambda^2 D t}$$

Boundary condition:

$$\frac{\partial X(0)}{\partial x} = 0 \Rightarrow B=0$$

$$X = A \cos(\lambda x)$$

Drying problem:

$$\frac{\partial X}{\partial x} \geq 0 \Rightarrow X = A \cos\left(\frac{n\pi x}{2b}\right) \quad n=1, 3, 5, \dots$$

$$u(x, t) = \sum_{n \text{ odd}} A_n \cos\left(\frac{n\pi}{2b} x\right) e^{-\frac{n^2 \pi^2 D}{4b^2} t}$$

$$u(x, 0) = \sum_{n \text{ odd}} A_n \cos\left(\frac{n\pi}{2b} x\right)$$

$$A_n = \frac{2}{b} \int_0^b u(x, 0) \cos\left(\frac{n\pi}{2b} x\right) dx$$

$$= \frac{4}{n\pi} \int_0^{\frac{n\pi}{2}} u(x, 0) \cos\left(\frac{n\pi}{2b} x\right) d\frac{n\pi x}{2b}$$

$$= \frac{4}{n\pi} u(x, 0) (-1)^{\frac{n-1}{2}}$$

$$\text{Set } u(x, 0) = 1 \Rightarrow u(x, t) = \sum_{n \text{ odd}} \frac{4}{n\pi} (-1)^{\frac{n-1}{2}} \cos\left(\frac{n\pi}{2b} x\right) e^{-\frac{n^2 \pi^2 D}{4b^2} t} \quad \text{FINE}$$